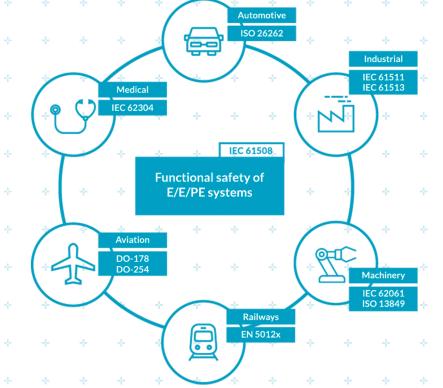
arm

Safety Ready for Cortex-M

Arm's functional safety run-time system for Cortex-M applications with our certified RTX5 RTOS and C/C++ toolchain – optimized for MDK-Professional. | keil.com/fusa-rts

Arm FuSa RTS Run-Time System for Functional Safety Applications



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Arm FuSa RTS is a set of embedded	
for use in the most safety-critical 🐳	
medical and industrial systems.	
With the FuSa RTS developers receive a robust real-time operating+	
processor abstraction layer and verified C library that are highly	
optimized for Cortex-M processors by Arm architecture experts.	
Safety-qualified Arm C/C++ compiler, Arm Keil MDK tools and FuSa RTS	
components are natively integrated together and significantly simplify	÷
validation and certification processes	
tor safety applications.	
	software components qualified for use in the most safety-critical applications in automotive, medical and industrial systems. With the FuSa RTS developers receive a robust real-time operating system (RTOS), independent processor abstraction layer and verified C library that are highly optimized for Cortex-M processors by Arm architecture experts. Safety-qualified Arm C/C++ compiler, Arm Keil MDK tools and FuSa RTS components are natively integrated together and significantly simplify system design, development,



Arm FuSa RTS: Run-time system for	Software components certified for safety-critical applications						
functional safety	User Application code			Covered safety standards: + Automotive:			
	FuSa RTX RTOS Events Mutex Thread Semaphore RTOS Time RTOS Scheduler Memory	FuSa Event Recorder	Software test library (STL) Self-test code for run-time verification	ISO 26262, ASIL D + Industrial: IEC 61508, SIL 3 + Medical: IEC 62304, Class C + Railway:			
	FuSa CMSIS-Co (Arm-Core speci		CMSIS-Core (device-specific)	EN 50128, SIL 4 Supported processors:		EN 50128, SIL 4	
	FuSa C library		+ Cortex-M0/M0+ + Cortex-M3				
FuSa RTS components certified with safety Arm C/C++ Compiler	Arm Cortex-M processor+ Cortex-M4+ Cortex-M7						
FuSa RTS Licensing	Straightforward licensin	ig with trans	sparent project c	osts			
	+ Limited to a particular Cortex-M core		y-free, ndent on the tion volume	+ One-time fee per development project (incl. 1 year S&M)			
FuSa RTS benefits	Fast-Track to functional safety applications						
	 + FuSa RTS is certified in combination with safety qualified Arm compiler + Keil RTX5 provides dynamic and static memory allocation for RTOS objects + Event Recorder helps during software development by providing kernel information, user event annotations, and timing information of the application + The FuSa CMSIS-Core implements the basic run-time system for a Cortex-M device and gives you access to the processor core + The FuSa C library implements subset of functions specified in the ISO C99 C language standard and comes with usage guidelines and examples on how to work effectively with it. 						
Arm Keil MDK development system for FuSa	Compiler, IDE and debugger accelerate the development and verification process						
Feature							
Safety-qualified Arm C/C++ compiler	MDK-Professional edition grants free access to safety-qualified Arm C/C++ compiler and its supporting documentation						
Static code analysis and MISRA checking	MDK provides native integration with code verification tools such as PC-lint and Parasoft C/C++ test.						
Code coverage	MDK with ULINKpro enables non-intrusive code coverage on target hardware via streaming instruction trace.						
Continuous integration	MDK has a command line interface for test automation and integration with Continuous Integration (CI) tools such as Jenkins						
Simulation models	MDK-Professional enables robust regression testing at function and module level using Fixed Virtual Platforms (FVP) models.						
RTOS -aware debugging	MDK Component Viewer allows memory analysis for optimizing FuSa RTS object allocation (dynamic vs static).						
Timing analysis	Event Recorder provides status details of software components and includes time information. Execution statistics show average, min and max execution times.						



TECNOLOGIX s.r.l.

Via dei Biancospini, 6 | 20146 Milano | Italy Tel +39 02 48954230 | Fax +39 02 471106 info@tecnologix.it | www.tecnologix.it

